

Project Name:

Smart Elevator Access Project (AAEP)

Big Idea:

AI for Equal Urban Accessibility

Essential Question:

How can we ensure public
infrastructure serves those who
need it most?

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School : Kütahya Science And Art Center



The Broken Promise

Overpass elevators are built for those who need them. But misuse by the general public leaves them broken, abandoned, and inaccessible.



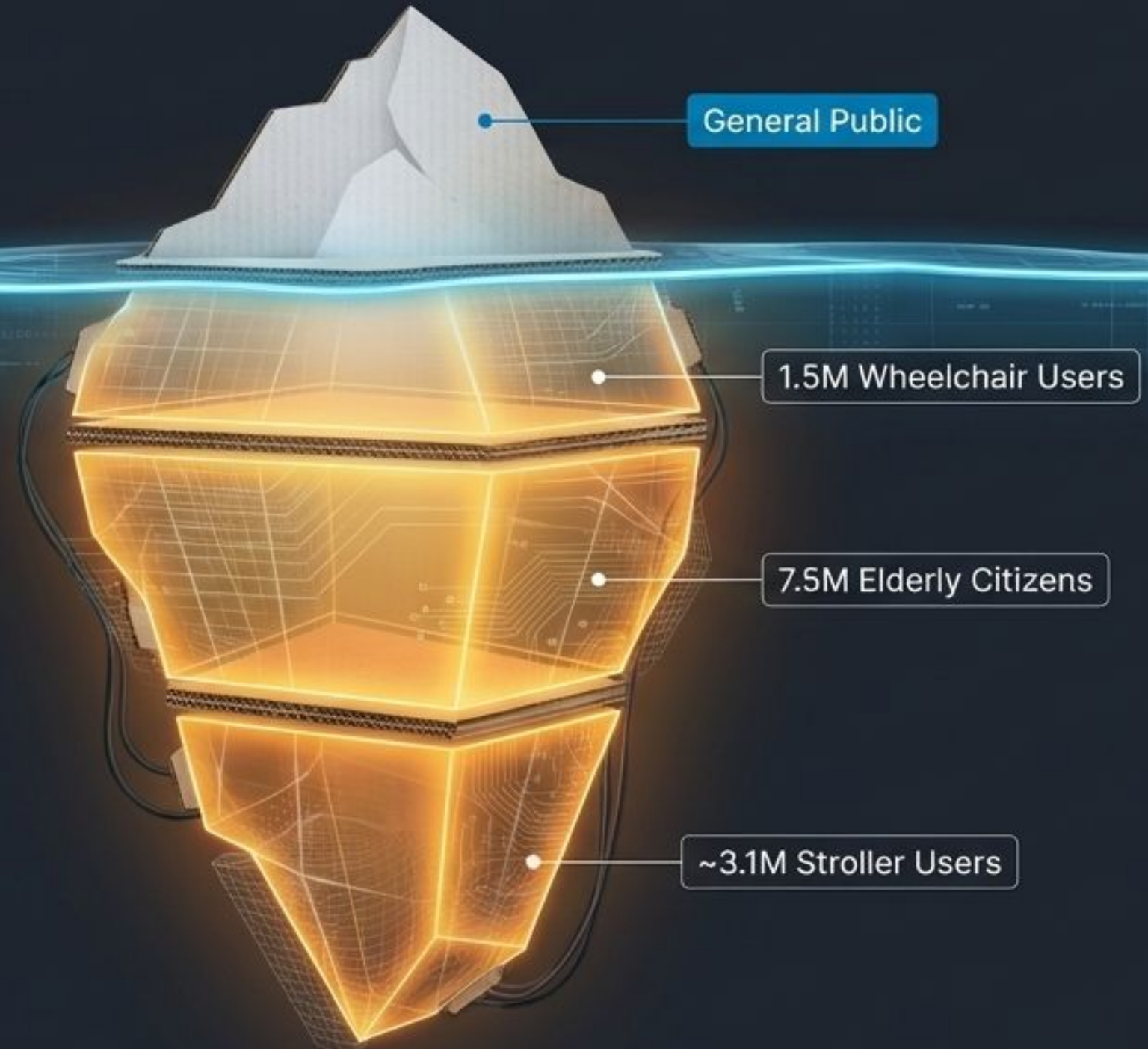
Empathizing with the Friction

A minor inconvenience for us. An insurmountable wall for them.



The Scale of the Invisible Need

In Türkiye



Over 10.5% of the population is left behind by failing infrastructure.

**Vulnerable
Users Stranded**
(Target demographic
loses access)



**The
Accessibility
Trap**



**Healthy User
Misuse**
(Elevators treated as
conveniences)



**Accelerated
Wear & Tear**
(Frequent breakdowns and high
municipal maintenance costs)

CHALLENGE

How do we stop elevator misuse without adding physical barriers for those who truly need access?

[The answer: We remove the buttons.]

Investigating the Solution: An AI Ecosystem

Replacing physical keys with Artificial Intelligence.



The Eye
(Input)

The Brain
(Processing)

The Muscle
(Action)

The Brain: Machine Learning

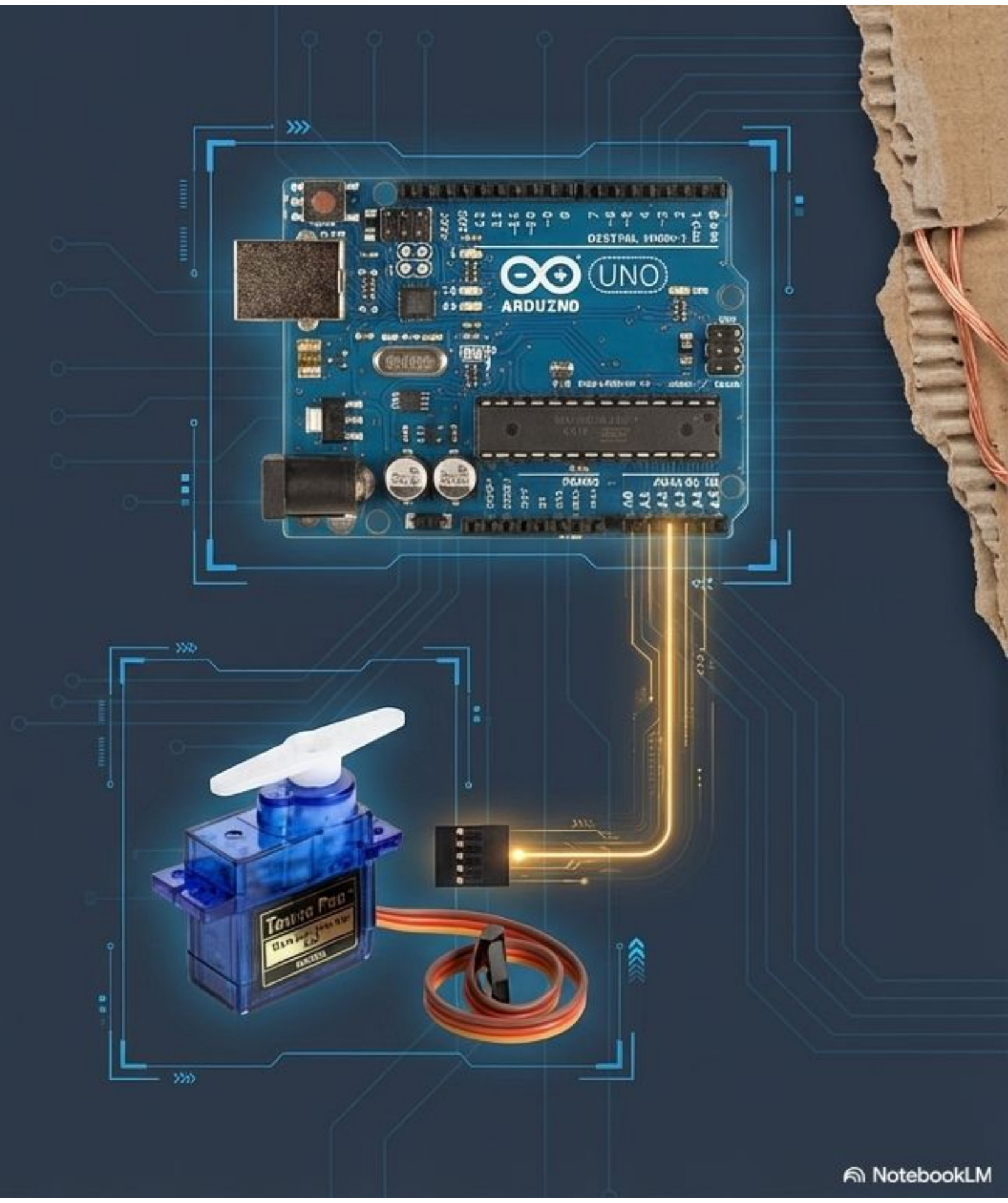
We investigated Pictoblox to train a custom computer vision model. By feeding it data, the AI learned to "see" and classify wheelchairs, the elderly, and strollers in real-time.

The screenshot displays the Pictoblox interface for training a custom computer vision model. On the left, there are four data classes: 'sandalye' (85 Image Samples), 'diğer' (17 Image Samples), and 'yaşlı' (14 Image Samples). Each class has a 'Webcam' and 'Upload' button. In the center, a 'Training' panel shows 'Model Trained' and 'Advanced' options. On the right, a 'Preview' panel shows a live webcam feed of a person pushing a stroller. Below the feed, an 'Output' section displays classification results: 'yeşil' (green), 'araba' (car) with a blue bar and 'yes' label, 'sande...' (stroller), and 'diğer' (other). A blue arrow points from the 'Real-time visual classification' box to the 'araba' bar.

Real-time visual classification

The Muscle: Microcontrollers in Tech Blue

We learned how to use the Arduino Uno to translate digital AI decisions into physical, mechanical action—triggering a 180-degree servo motor to unlock and open doors.

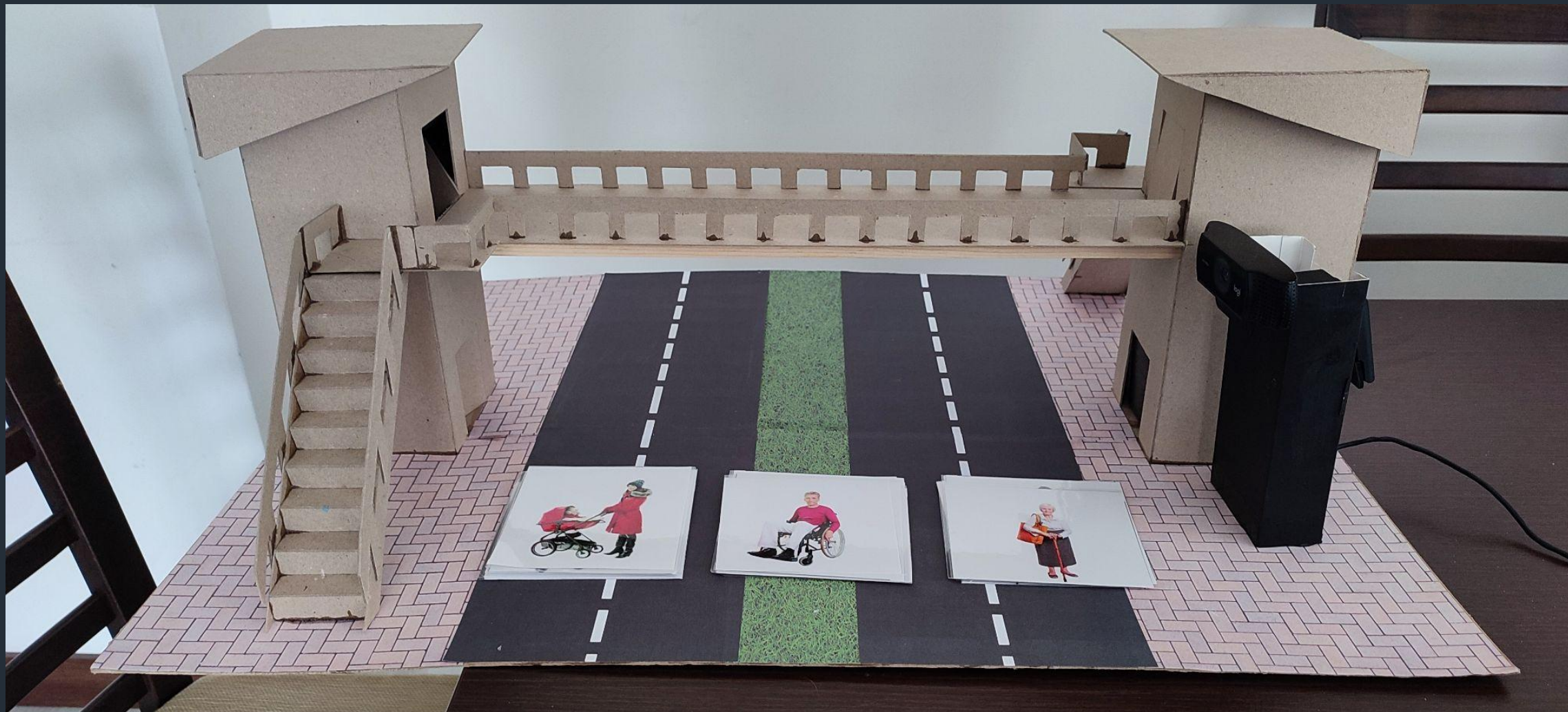


Old Paradigm vs. Smart Paradigm

	Current State	Smart AI State
Access Method	Standard Push-Button (Open to all)	AI-Vision (Restricted to verified users)
Misuse Rate	High (Convenience usage)	Zero (System ignores unauthorized users)
Availability	Frequently Broken	Always Available & Low Maintenance

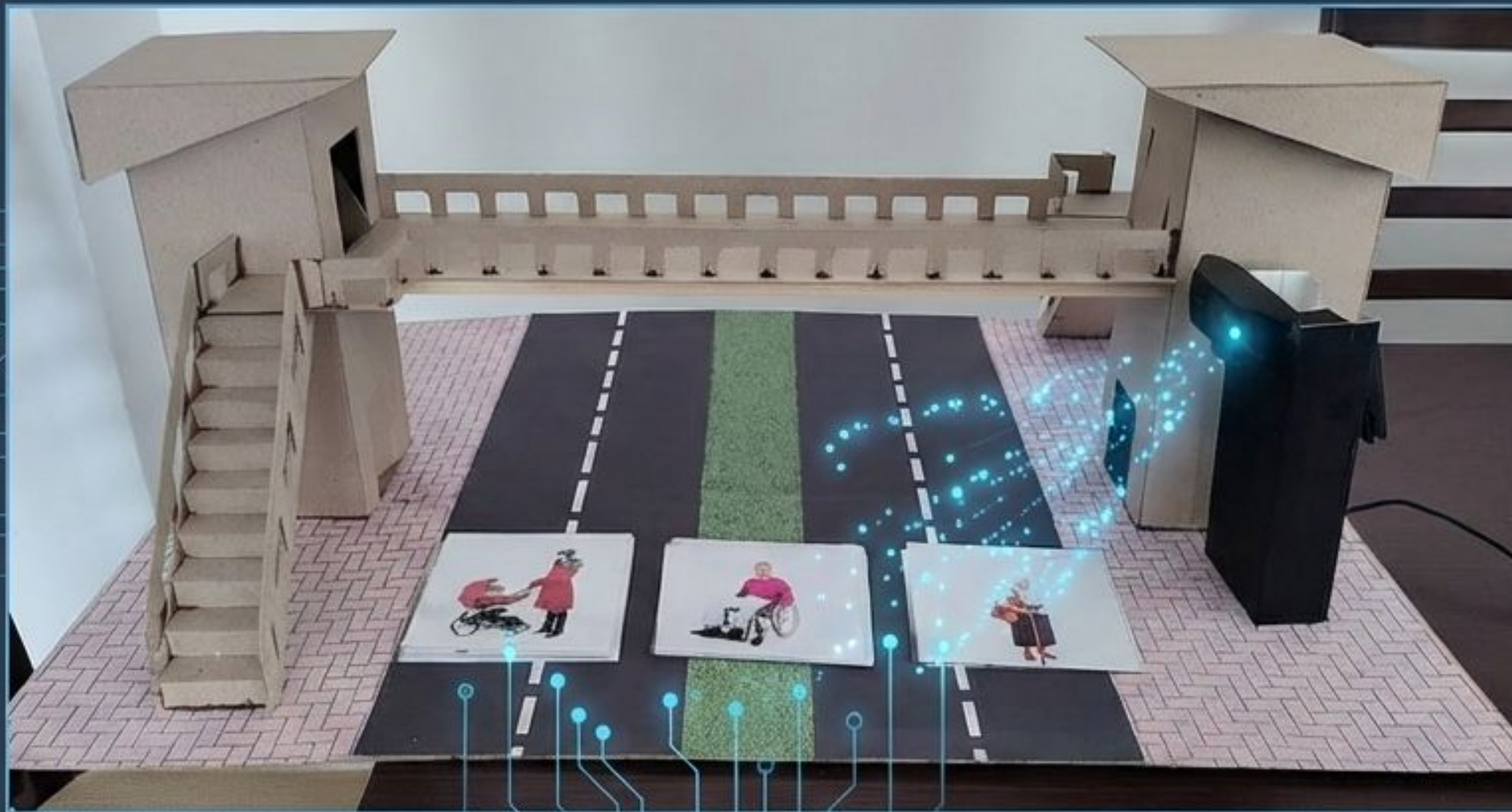
Action Step 1: The Physical Build

We scaled down the city to cardboard. Our prototype features a functioning camera mount and a motorized elevator door system.



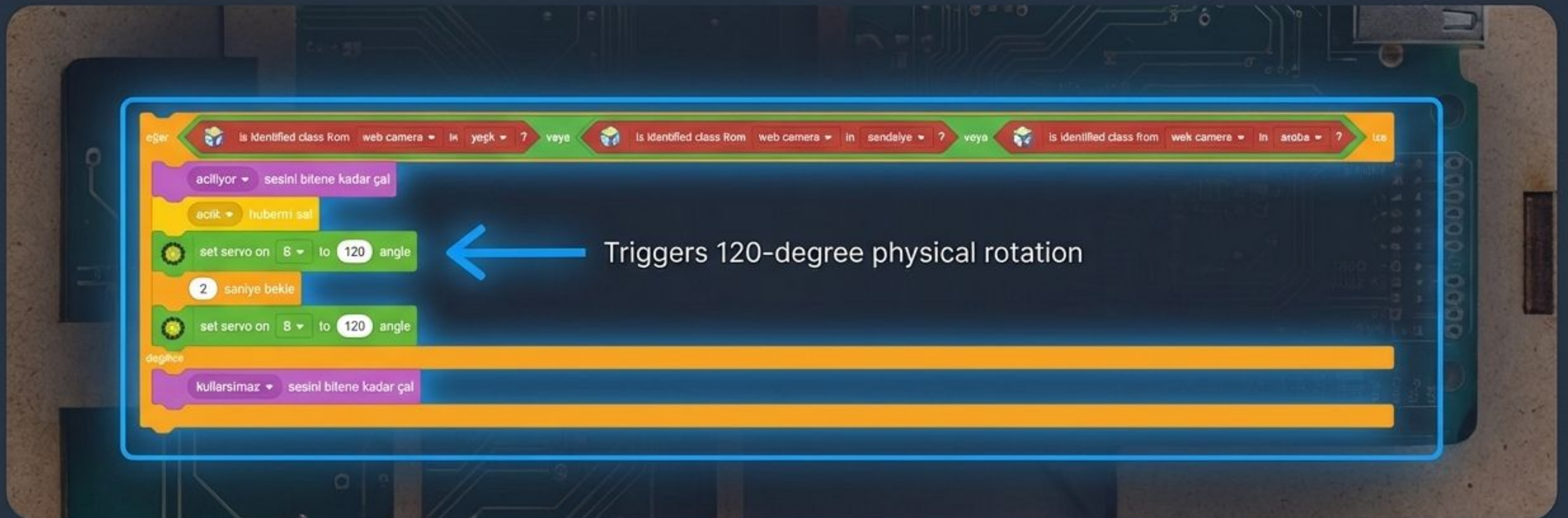
Action Step 2: Training the AI

We fed hundreds of image samples into our Pictoblox model. The AI rigorously learned to differentiate our target users from the general public with high accuracy.



Action Step 3: Writing the Logic

Bridging software and hardware. If the AI detects a verified user, the script commands the Arduino to rotate the servo, instantly opening the door.



The Prototype in Action

Digital intelligence meets physical accessibility.
The door only opens for those who truly need it.

STEP 1
INPUT



STEP 2
PROCESS



STEP 3
OUTPUT



The Future of Accessible Cities

- ✓ Less municipal downtime.
- ✓ Zero system misuse.
- ✓ True social equality.

**Technology is only as smart as the people it helps.
Let's build cities for everyone.**